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# AI in Physical Form: The Rise of Robots and Humanoids

HUMAN-MACHINE SYSTEMS | EMBODIED INTELLIGENCE |  
ADAPTIVE AUTOMATION



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## Preface

As a Senior Fellow at The Digital Economist and a long-time operator across product, marketing, and partnerships, I have witnessed multiple waves of automation reshape work, productivity, and global growth. Embodied AI—systems that combine artificial intelligence with robotics and physical interaction—marks a new inflection point. Embodied AI is demonstrated in systems like Tesla’s Optimus humanoid robot and NVIDIA’s GROOT-powered Figure 01, which combine perception, multimodal intelligence, and physical action to operate autonomously in the real world.

We are moving beyond earlier automation waves—from industrial robotics to digital process automation—into a world where machines can perceive their surroundings, plan complex sequences, and act safely in human environments.

Against this backdrop, the paper serves as a field guide for executives, policymakers, and innovators seeking to separate signal from noise. As a field guide, it offers strategic frameworks and decision-making tools to help organizations adapt effectively, such as the flywheel for physical AI. It explains where value will emerge, which risks demand urgent governance, and how leaders can capture advantage responsibly. Whether in manufacturing, logistics, healthcare, or education, the shift to physical AI is not an abstract future—it is an unfolding business reality that will define competitiveness in the decade ahead.



## At a Glance

AI is taking physical shape in robots and humanoids—embodied systems that can perceive, decide, and act in the real world. The payoff is measurable safety, consistency, and resilience in logistics and manufacturing today, with expanding roles in elder care, field service, and construction tomorrow.

As adoption accelerates, these systems promise economic efficiency and new capabilities, but they also bring tangible risks: safety incidents, workforce anxiety, privacy exposure, and unclear accountability. To navigate this shift successfully, leaders should treat embodied AI as a long-term platform, not a quick automation fix—starting with high-yield tasks, designing with workers in mind, aligning with global standards, and measuring outcomes with the same rigor applied to digital transformation initiatives. The flywheel is a great way to frame your strategic intent.



## Executive Summary

Artificial intelligence has matured from predicting clicks and generating text to guiding machines that touch the physical world. The move from cognitive to embodied AI represents one of the most profound industrial transitions—a shift comparable in scale to electrification. Intelligent machines are no longer research curiosities; they are moving from prototype to limited production in logistics, automotive, and precision assembly.

The early wins concentrate on where workflows are repetitive, layouts are structured, and safety programs are robust. Companies report three primary waves of benefit:

- **Safety and Well-Being:** Robots now remove people from repetitive lifts, toxic exposure, and ergonomic strain, reducing lost-time injuries and insurance costs—for example, by taking over hazardous chemical handling in semiconductor fabs.
- **Quality and Predictability:** Automated movements deliver micrometer precision and stable cycle times, driving better product consistency and real-time data visibility, such as robotic arms performing exact adhesive placement in electronics assembly.
- **Continuous Operations:** Fleets extend uptime into night shifts without fatigue, raising utilization rates of existing capital assets and reducing dependency on shift scheduling and labor shortages. For instance, whereas robots continue inventory picking and replenishment long after human teams leave.



Humanoids extend this frontier further. Their anthropomorphic form allows them to use existing doors, stairs, and tools without major retrofits. Notably, in dense facilities with fixed physical layouts, this compatibility shortens integration timelines and accelerates ROI compared to bespoke automation.

The NVIDIA CFO commented on the Q3 earnings call: “Physical AI is already a multibillion-dollar business addressing a multitrillion-dollar opportunity, and the next leg of growth for NVIDIA. Leading US manufacturers and robotics innovators are leveraging NVIDIA’s three computer architectures: to train on NVIDIA, test on Omniverse computers, and deploy real-world AI on Jetson robotics computers.”

Still, the opportunity is bounded by engineering limits and human factors. Even with major gains in energy storage, battery constraints still cap operational duration and require facilities that support in-environment charging. Dexterity remains brittle in cluttered or unmodeled spaces. Edge-case failures cause downtime, and trust erodes quickly when workers are excluded from the design process.

Success requires not just smarter machines but adaptive organizations—those that embed transparency, ethics, and worker dignity at the core of their strategy while matching form factor to task and instrumenting every deployment for continuous learning. And for the home, adaptive robots that focus on a specific task, maybe not the full humanoid yet.





# 1.

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## Introduction: The Era of Physical AI

While the terms “physical AI” and “embodied AI” are often used interchangeably, they represent distinct but overlapping concepts. Physical AI refers to AI systems that interact with and manipulate the physical world through robotics, sensors, and actuators. Embodied AI, more specifically, emphasizes systems where physical form and sensorimotor experience are integral to learning and cognition because intelligence emerges through bodily interaction with the environment.

Physical AI fuses cognition with motion. Imagine a robot delivering a pizza to your home: it steps through the doorway into the kitchen, serves the meal, pours beverages—perhaps choosing Coca-Cola—waits as dinner concludes, then clears the plates, washes them, and quietly exits. This scenario is no longer science fiction; it is already unfolding in a garage in Silicon Valley.

For decades, industrial robots performed the same trajectories inside guarded cages—powerful yet blind to change. The new generation perceives, reasons, and acts within dynamic settings. Using multiple cameras, depth sensors, and tactile inputs, these systems create rich internal maps of the world, adjust to variation, and coordinate smoothly with people.

This transformation did not appear overnight. Three underlying technology trends converged:

- **Sensor Revolution:** Affordable lidar, depth cameras, and force sensors now capture the environment at millisecond intervals, feeding continuous 3D perception.

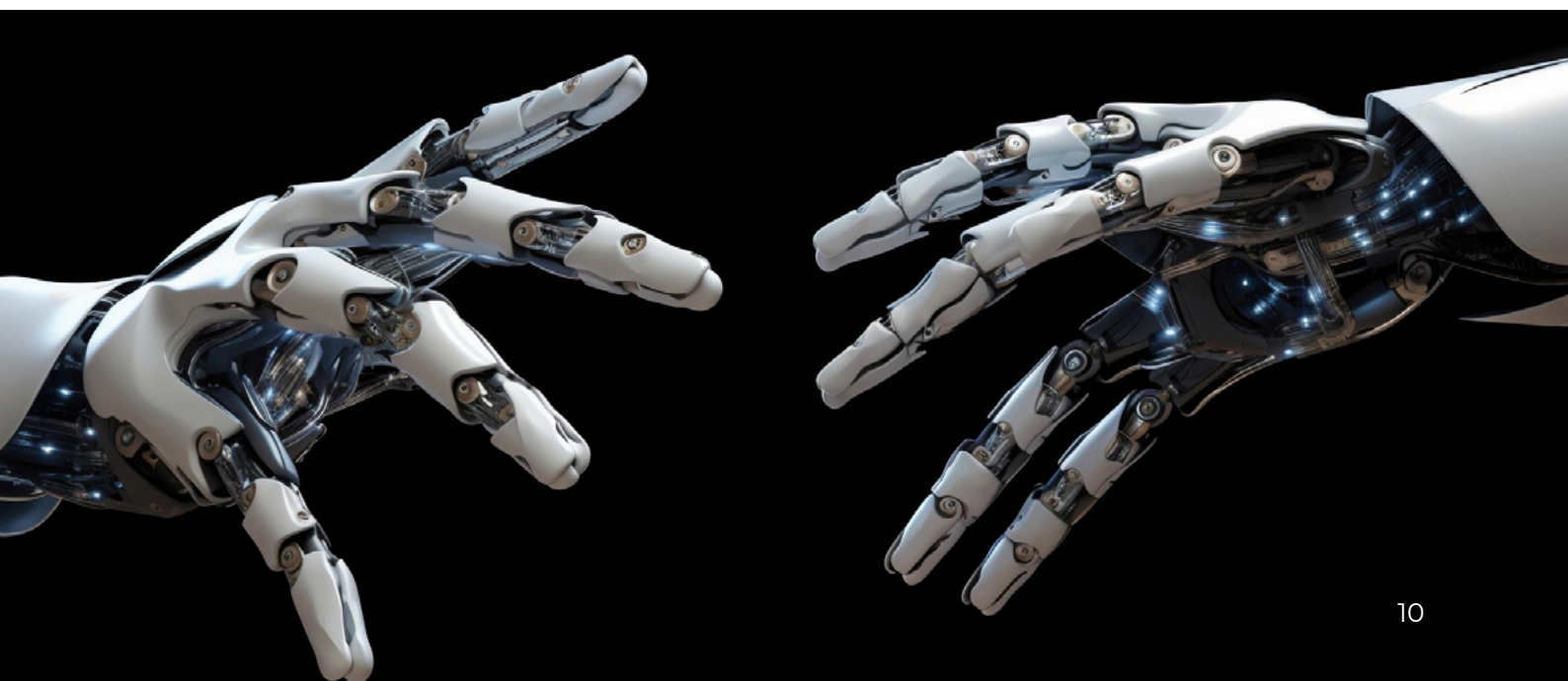


- **Compute Density:** Edge GPUs and specialized inference chips process massive sensor data locally, enabling real-time responses rather than the latency of remote commands.
- **Learning Infrastructure:** Digital twins and simulation engines—such as NVIDIA Isaac Sim or Unity Robotics—allow millions of virtual trials before a single physical movement occurs.

Together, these advances allow machines to plan and act autonomously in semi-structured environments such as warehouse aisles, factory cells, hospital corridors, and modern elder care facilities where mobility support and routine assistance are in high demand.

Robots and humanoids share a single aim: delivering useful work. Robots excel at narrow, repetitive tasks—welding, painting, palletizing, bin-picking—where consistency rules. Humanoids trade some speed and payload for adaptability: they can climb stairs, open doors, and manipulate the same tools humans use. Most enterprises will adopt a hybrid model, combining fixed automation for throughput with mobile manipulators and humanoids for flexibility. This hybrid approach maximizes both efficiency and versatility, enabling organizations to scale operations while remaining responsive to change.

At a societal level, this era mirrors the computerization of offices in the 1980s: a silent revolution in the distribution of capability. Organizations that ignore spreadsheets fall behind; those that ignore embodied AI risk falling behind in productivity, competitiveness, and innovation.





## 2.

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### Market Landscape: Robots and Humanoids

The robotics market today spans three overlapping domains—industrial, service, and humanoid—each with distinct economics and maturity curves.

- **Industrial Robots:** These systems account for more than 4.3 million operating units worldwide, according to the International Federation of Robotics (IFR).<sup>1</sup> Automotive and electronics manufacturers lead adoption, with automation density exceeding 1,000 robots per 10,000 workers in some plants. The next growth phase lies in mid-sized suppliers and process industries, where collaborative robots (“cobots”) enable safer human-machine cooperation without the need for fencing.
- **Service Robots:** Logistics and retail drive this segment. Amazon Robotics’ mobile fleets, Boston Dynamics’ Stretch, and Chinese providers such as Geek+ and HaiPick have automated internal transport at a global scale. Hospitals deploy delivery robots for linens and medications while hospitality providers use them for room service and cleaning. These platforms integrate navigation, perception, and manipulation into cohesive stacks. For example, Amazon Robotics transformed warehouse automation by deploying more than 750,000 mobile robots, improving fulfillment efficiency by over 25 percent and reducing average order processing time from hours to minutes.



- **Humanoids:** The newest and fastest-growing class focuses on versatility over specialization. Tesla's Optimus, Figure AI's Figure 01, Agility Robotics' Digit, Sanctuary AI's Phoenix, and Unitree's H1 illustrate divergent design philosophies—from electric-actuated efficiency to high-fidelity dexterity.<sup>2,3,4</sup> Early pilots target part transport, kitting, and light assembly, where human ergonomics previously limited automation. Analysts forecast the humanoid market could reach \$15 billion by 2030 and \$50 billion by 2035 if reliability and cost curves hold.
- **Ecosystem and Competition:** Traditional giants (ABB, FANUC, KUKA, Yaskawa) dominate mature sectors through scale and service networks.<sup>5,6</sup> Startups differentiate via AI software and lightweight hardware. Semiconductor leaders (NVIDIA, Intel, Qualcomm) and cloud providers (AWS, Microsoft Azure) now anchor the embodied-AI platform layer, creating developer ecosystems that mirror the smartphone era.
- **Geography and Policy:** Asia leads in deployment volume and government investment. China's Ministry of Industry and Information Technology has prioritized humanoid robotics as a national pillar, aiming to deliver affordable units priced under \$20,000 within five years.<sup>7</sup> Japan focuses on elder-care and service robots aligned with its aging demographics. Europe advances more slowly but emphasizes safety certification and union participation, creating trust advantages. The US emphasizes commercial speed and venture-driven scaling, especially in logistics and defense.
- **Public and Government Adoption:** Defense and civil-protection agencies increasingly test humanoids for hazardous response, inspection, and space operations. NASA's Valkyrie program and the US Air Force's collaborative-robot initiatives highlight how embodied AI is moving beyond factory floors into high-risk, high-stakes environments. These programs demonstrate the reliability and adaptability of humanoids under extreme conditions, providing critical proof points that accelerate both industrial adoption and venture-driven scaling across sectors such as logistics, defense, and emergency operations.

The market is no longer waiting for perfect machines; it rewards usable reliability. Cost reductions of 10 to 15 percent per year across sensors, batteries, and actuators are pushing robotics from bespoke capital asset to subscription service—"Robot-as-a-Service." Over the next decade, expect convergence between industrial maturity and humanoid flexibility to shape intelligent labor.



Category	Industrial Robots	Service Robots	Humanoid Robots
<b>Economics</b>	~4.3 million units worldwide; typical cost: \$30K–\$150K per robot. High ROI in automotive/electronics; payback in 1–2 years for high-volume plants.	Rapid adoption in logistics, healthcare, and retail; cost varies (\$10K–\$100K/unit). ROI depends on scale—large retailers report <2-year payback.	Market expected to reach \$15B globally by 2030 and \$50B by 2035; early units cost \$50K–\$200K. ROI is challenging, but integration savings are possible in dense facilities.
<b>Deployment</b>	Common in structured settings (factories, assembly lines); highest density in Asia—Japan, South Korea, and China.	Deployed in warehouses, hospitals, hotels, and stores; China, the US, and Europe, showing strong growth.	Early pilots in manufacturing, logistics, and elder care; China leading in volume and government support; Japan focuses on aging care, the US on logistics and manufacturing.
<b>Typical Functions</b>	Welding, painting, picking, palletizing; repetitive, high-precision tasks.	Navigation, material transport, delivery, cleaning, and customer assistance.	Part transport, kitting, basic assembly, guidance in healthcare, and limited direct interaction with humans.
<b>Regional Differences and Impact</b>	Asia: Largest volume, aggressive R&D and government policy incentives (e.g., China targeting units <\$20K); Europe: Slower adoption, stricter safety standards, union involvement; US: Fast commercial scaling, policy favoring innovation.	China: Scale and price lead; Europe: Safety/certification focus, public trust advantages; US: Market-driven, logistics-focused.	China: Prioritizes affordability and mass deployment; Japan: Dignity and elder care focus; Europe: Safety and ethics lag but foster public trust; US: Emphasizes speed and venture funding.

Table 1. Categories of robots and humanoids



# 3.

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## Technology Stack: From Perception to Control

Embodied AI rests on a layered stack that turns perception into purposeful motion. It integrates sensors, computing, algorithms, and actuators into a unified control system that operates at humanlike reflex speeds. At the foundation are sensing technologies that have advanced dramatically over the past five years. High-resolution stereo cameras, depth sensors, force-torque sensors, and tactile arrays now allow robots to map their environment with millimeter-level precision.

Above the sensory layer, perception models transform raw data into semantic understanding. They identify objects, surfaces, and people, classifying them by shape, texture, and behavior. This enables robots to distinguish a screwdriver from a wrench or a person from a pallet. In humanoids, multimodal perception also processes auditory and linguistic cues, supporting contextual decision-making in noisy or variable settings.

The planning layer converts this understanding into actionable steps. Path-planning algorithms evaluate dynamic obstacles, energy efficiency, and mechanical constraints to generate motion paths that balance speed and safety. Control systems then translate these abstract plans into precise torque commands for every joint and motor. High-frequency feedback loops—often operating hundreds of times per second—ensure smooth and adaptive movement even when the environment shifts unexpectedly.



A new ingredient in this stack is the rise of foundation models for robotics. These large, multimodal neural networks integrate text, vision, and motion data to build generalizable physical-world intelligence. Because foundation models are better suited to dynamic environments and accelerate RL training cycles, engineers can skip hardcoded control algorithms and fine-tune models that already grasp spatial relations, cause and effect, and tool use. NVIDIA's GROOT and Google DeepMind's RT-X illustrate how skill transfer across simulations and real-world data enables faster deployment.<sup>8</sup>

Simulation now plays a pivotal role in this ecosystem. Before any real-world motion occurs, robots undergo millions of synthetic training iterations in virtual environments with accurate physics. This approach reduces risk, cost, and downtime. Digital twins extend the concept further, maintaining continuously updated virtual replicas of physical assets to support predictive maintenance and real-time optimization.

Along with physical reliability, a significant limitation is mapping abstract or non-concrete steps, which remains one of the hardest challenges in physical AI. The Stanford professor, Dr. Fei Fei Li, spoke about this recently, highlighting how robots still struggle to translate high-level intentions into precise, sequential actions.

Hands remain the holy grail of humanoid design. Human dexterity relies on subtle coordination of force, compliance, and proprioception that robotic grippers have yet to match. While many humanoid teams attempt to close this dexterity gap through ever-more complex grippers, Dr. Aadeel Akhtar and his company Psyonic, take a different, deeply human-centered approach. Their Ability Hand focuses on restoring not just mechanical function but feeling—incorporating high-speed sensors, compliant materials, and tactile feedback that mimics the micro-adjustments humans make without thinking. Akhtar often says that a hand is not just a tool but an extension of identity, agency, and connection. By prioritizing real-world durability, responsiveness, and the ability to sense pressure and texture, Psyonic shows that robotic hands do not need to perfectly copy biology to deliver human-level usefulness. Instead, they need to understand what matters most to the user: control, confidence, and the ability to interact with the world naturally.



Material science and actuator design must advance alongside AI for humanoids to reach large-scale viability. The future will depend not only on better models but also on more durable components that withstand long duty cycles, dust, vibration, and environmental stressors.





## 4.

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### **Economics and Workforce Impact**

The economic impact of robots and humanoids is both immediate and long-term. In the short term, the business case centers on safety, quality, and efficiency. Each workplace injury avoided saves companies tens of thousands of dollars in compensation and lost productivity. Robots that maintain constant cycle times reduce defects and stabilize production schedules, yielding cost savings that compound over time.

However, the deeper transformation lies in how organizations rethink productivity. Traditional automation improved output per worker by eliminating repetitive motion. Embodied AI improves output per workflow by blending human judgment with machine endurance. Workers shift toward supervision, coordination, and creative problem-solving while machines handle the mechanical, high-frequency tasks.

- Return on investment varies widely by industry and task. In logistics, pick-and-place robots often recoup costs within two years due to reduced injury and extended uptime. In manufacturing, ROI depends on volume stability and process standardization. Humanoids are initially more expensive, but their ability to operate within existing human-designed environments avoids costly facility redesigns. Analysts from McKinsey and BCG estimate that as hardware prices fall and reliability improves, embodied AI could contribute between one and four trillion dollars in global economic value annually by 2035.



- Labor implications are complex. Robotics adoption tends to shift rather than eliminate employment. For every job displaced in repetitive manual work, new roles emerge in system monitoring, maintenance, AI training, and data analytics. Companies that invest in retraining can convert disruption into long-term capability. Amazon's Mechatronics and Robotics Apprenticeship program and BMW's reskilling initiative for assembly-line workers offer early examples of how automation can support workforce evolution rather than attrition.<sup>9</sup>
- Cost curves reinforce the trend toward scalability. Motors, sensors, and batteries continue to decline in price by roughly 10 to 15 percent annually. Software reusability across fleets amplifies returns, turning once-custom systems into replicable platforms. As integration costs fall, mid-market manufacturers and service providers gain access to robotics previously reserved for large corporations.

#### 4.1 Emerging Jobs in the Age of Robots and AI

As AI and robotics reshape entire industries, a paradox emerges: automation eliminates some traditional roles while simultaneously creating new categories of work that did not exist just a few years ago. Rather than replacing human workers outright, intelligent machines generate demand for professionals who bridge human judgment and artificial capability. These roles require a unique blend of technical fluency and human insight—precisely because people remain essential for guiding, overseeing, and optimizing automated systems.

- **AI Trainers and Prompt Engineers:** Supervise, guide, and improve human-robot or human-AI interactions, as well as those who develop and fine-tune prompts, and refine conversational scripts for generative systems.
- **AI Ethicists and Explainability Experts:** Ensure algorithm fairness, transparency, and responsible deployment decisions.
- **Robotics Operations and Monitoring Specialists:** Oversee robot fleets, maintain operational uptime, troubleshoot, and optimize workflows, especially in logistics and manufacturing.
- **AI-Enhanced Healthcare Technicians:** Support robot-assisted care, remote diagnostics, and wearable exoskeletons in clinical and home settings.



- **Data Annotators and Simulation Designers:** Build and maintain digital twins, simulation environments, and training datasets.
- **AI/Robot Safety Auditors and Cybersecurity Analysts:** Safeguard intelligent machines against physical and digital risks.
- **Reskilling Facilitators and Apprenticeship Coordinators:** Lead workforce transition programs and retraining pathways.

Ultimately, embodied AI reshapes not only the cost structure of work but its meaning. The most successful firms will integrate human creativity with robotic endurance to build hybrid organizations where machines extend—rather than replace—human potential.





## 5.

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### **Societal Benefits and Goodness**

The arrival of robots and humanoids is not merely an industrial upgrade; it carries profound social potential. The most visible benefit is safety. Machines can take on tasks that expose humans to physical harm, toxic substances, or extreme fatigue. In warehouses and factories, collaborative robots already reduce musculoskeletal injuries by taking over lifting, stacking, and repetitive reaching. This shift protects workers' health, reduces absenteeism, and strengthens morale.

A second major benefit is demographic resilience. Many advanced economies face aging populations and shrinking labor forces. Japan, Germany, and South Korea are already deploying assistive robots to supplement caregivers, providing mobility support, patient monitoring, and routine assistance in nursing facilities. As dexterity improves, humanoids could enable older adults to remain independent longer—improving quality of life while easing caregiver shortages.

Sustainability represents another dimension of societal benefit. Robots and humanoids operate with consistent precision, leading to fewer defects, reduced waste, and optimized energy use. Fleet-level analytics can reveal inefficiencies invisible to human observation, helping companies lower emissions per unit of output. In agriculture, AI-driven robots can target fertilizer and pesticide application with high precision, conserving resources while reducing environmental impact.



Education and inclusion also stand to benefit. Schools and universities are using low-cost educational robots to teach programming, robotics, and ethics to students from diverse backgrounds. Exposure to these tools early in life builds technical literacy and demystifies AI. For people with disabilities, physical AI promises new forms of accessibility—from robotic assistants that fetch objects to exoskeletons that restore mobility.

At a broader level, the overarching gain lies in human dignity. When designed responsibly, embodied AI can remove drudgery and risk from work, freeing people to pursue higher-level creativity, empathy, and strategy. It can make workplaces safer, communities more resilient, and services more inclusive—if, and only if, ethics and accountability evolve in tandem with technology.

Futurist and early humanoid adopter Robert Scoble offers a compelling illustration of how physical AI can directly improve household well-being and one of the most overlooked societal benefits. After several years running a busy Silicon Valley household while experimenting with advanced robotics, Scoble has owned both a \$20,000 Neo humanoid and a \$1,500 Posha cooking robot. His conclusion reframes the conversation: “We are thinking of robots all wrong. We obsess over humanoids when the real revolution starts with dinner.”

He argues that the true “low-hanging fruit” for improving daily life is not cleaning or laundry but food preparation because it absorbs more time, shapes nutrition, and influences family health outcomes.

Seen through this lens, the social impact becomes clearer. A family of four that routinely spends more than \$100 on restaurant meals or defaults to ultra-processed, microwave options due to time scarcity can instead use a cooking robot to produce fresh, healthier meals for under \$20 in ingredients, while reclaiming meaningful time for children, rest, or learning.

While humanoids still lack the dexterity and safety guarantees to manage open flames or sharp tools, they can complement specialized kitchen systems by setting tables, loading dishwashers, and reducing domestic strain. Scoble’s experience reinforces a core principle for the societal deployment of physical AI: empowering people by removing sources of stress and restoring time, dignity, and health, and not simply automating tasks for efficiency’s sake.



## 6.

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### **Risks and Ethical Challenges**

Every powerful tool introduces new vulnerabilities, and embodied AI is no exception. Risks span technical, legal, socioeconomic, and psychological dimensions, each requiring distinct governance responses. Safety is the most immediate concern. While strict standards already govern industrial robots, humanoids introduce new uncertainties because they move and operate in spaces built for humans. Preventing unintended collisions, mechanical failures, or software glitches requires rigorous testing, continuous monitoring, and reliable emergency stop procedures.

Liability is another gray zone. When a humanoid causes damage, responsibility can be ambiguous. Was it a programming fault, a maintenance lapse, or a design flaw? Legal systems have not yet evolved to address these distinctions. Insurers and regulators will need new frameworks to allocate risk between developers, owners, and operators.



Workforce disruption remains the most politically sensitive risk. Repetitive, physically demanding roles are most vulnerable to automation. Without proactive reskilling initiatives, workers may face income instability and psychological stress. Ethical deployment requires companies to reinvest a portion of their productivity gains into retraining, redeployment, and community education.

Privacy concerns will intensify as robots gain more advanced perceptual capabilities. Devices equipped with cameras and microphones could inadvertently capture sensitive information in workplaces or homes. Companies must implement strong data governance: on-device processing to minimize streaming, limited retention policies, and transparent disclosure about what is recorded and why.

Cybersecurity is a growing worry. Robots increasingly resemble networked computers with physical actuators. If compromised, they could cause physical harm or serve as entry points for broader cyberattacks. Best practices from IT—patch management, access control, encryption—must extend into operational robotics, alongside newer approaches such as zero-trust architecture.

Public acceptance cannot be taken for granted. Humans instinctively react to machines that resemble them. Too much realism can evoke discomfort, a phenomenon known as the uncanny valley. Designers are learning to craft humanoids that appear approachable but not human-like, balancing familiarity with clarity. Perceptions also vary across cultures; some societies are more open to humanoid robots than others. Transparency, honesty, and open communication matter more than anthropomorphic illusion.

Ultimately, the ethics of embodied AI hinge on human intention. While there is broad agreement that a set of governing principles or “laws” is needed to govern a future where humans and robots co-exist and even work side by side (the famous science fiction author Issac Asimov suggested the “Three Laws of Robotics” in his books as far back as 1942), there needs to be deep thinking put into what these governing principles should look like to protect humans, provide guardrails for robots, and be robust enough to withstand the test of time and the evolution of a robotic coexistence. If robots are built to augment human potential rather than replace it, and if their deployment is guided by empathy, accountability, and long-term thinking, then the age of physical AI can become a net positive force for humanity.



## **6.1 Checklist: Risks and Ethical Challenges**

As embodied AI systems move from controlled environments into homes, hospitals, factories, and public spaces, the risks surrounding their deployment become more immediate and multidimensional. These challenges aren't just technical. They span safety, legal responsibility, human rights, workforce impact, and societal trust. The following categories outline the core areas organizations must address to ensure responsible, resilient adoption of robots and humanoids at scale.

### **6.1.1 Safety**

- Physical harm from collisions, malfunctions, or unexpected movements.
- Inadequate emergency stop procedures or fail-safe mechanisms.
- Insufficient safety certification or maintenance oversight.
- Hazards from operating in close proximity to humans (e.g., cobots, humanoids in public spaces).

### **6.1.2. Liability**

- Ambiguity in determining fault for accidents (design, software, maintenance, or operator error).
- Lack of clear legal frameworks for accountability in cases of physical or financial harm.
- Insufficient incident reporting, insurance coverage, or claims processes.

### **6.1.3. Privacy**

- Risk of unauthorized data collection by sensors, cameras, and microphones.
- Inadequate transparency around how personal or sensitive data is stored and used.
- Potential exposure of proprietary or confidential information in workplaces or public areas



#### 6.1.4. Workforce Disruption

- Displacement of workers in routine, manual, or repetitive roles.
- Acceleration of de-skilling if upskilling/reskilling programs are absent or ineffective.
- Increased psychological stress and job insecurity in transition periods

#### 6.1.5. Public Acceptance

- Concerns over loss of human autonomy or increased surveillance.
- “Uncanny valley” discomfort from hyper-realistic humanoids or social robots.
- Lack of stakeholder and community engagement in deployment processes.

This checklist provides an actionable risk-awareness and mitigation framework for organizations and policymakers responsible for evaluating, deploying, or regulating robots and AI systems. Each risk should be paired with a robust response or management plan during system design, rollout, and operations.





# 7.

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## Case Studies and Signals

Real-world deployments show how embodied AI is moving from promise to practice. Each sector demonstrates unique adoption dynamics, offering early evidence of what works and what does not.

- **Logistics:** Large e-commerce and retail firms have become the most active experimenters. Amazon's collaboration with Agility Robotics uses the bipedal Digit robot to move totes across fulfillment centers, combining human flexibility with robotic endurance. Walmart and Ocado deploy fleets of mobile manipulators that load and unload bins in twenty-four-hour cycles. The business metric that matters most is intervention minutes per hour. "Intervention minutes per hour" measures how much time within each hour is spent on active, hands-on assistance or corrective action, rather than routine monitoring or passive activities. For example, in healthcare it tracks direct patient care time versus administrative tasks, while in education it might measure one-on-one tutoring minutes per class hour. This metric helps organizations make staffing decisions and demonstrate the intensity of their services with concrete, measurable data. The fewer human assists required, the higher the ROI. These trials also track ergonomic outcomes, showing significant reductions in strain injuries within one year of deployment.



- **Automotive:** Manufacturers such as BMW, Hyundai, and Tesla are testing humanoids for line-side logistics and parts delivery. BMW's partnership with Figure AI demonstrates how humanoids can navigate mixed environments without retooling conveyors or gates.<sup>10</sup> Tesla's Optimus project, tested within its own Gigafactories, focuses on predictable internal logistics and repetitive assembly motions.<sup>11</sup> Hyundai's acquisition of Boston Dynamics<sup>12</sup> integrates advanced mobility platforms into industrial and construction use cases, combining wheeled, legged, and drone systems. Most of these programs remain in early pilot or pre-production phases today, with broader commercial deployment expected to accelerate between 2026 and 2029 as reliability, cost curves, and safety certifications improve.
- **Electronics and Precision Manufacturing:** Collaborative robots equipped with advanced vision perform delicate insertion, soldering, and fastening tasks. Companies like Foxconn and ABB are integrating tactile sensing that allows sub-millimeter accuracy. In semiconductor plants, robots handle toxic materials in cleanrooms, eliminating exposure and ensuring consistency in wafer processing.<sup>13</sup>
- **Healthcare and Caregiving:** Hospitals in Japan and Singapore use humanoid-like service robots for patient guidance, medicine delivery, and elder-care assistance. These pilots focus as much on user comfort and trust as on efficiency. Robots must demonstrate predictability and politeness to be accepted in such personal contexts. Data collected from these programs help refine both motion behavior and social interaction models.
- **Public Sector and Extreme Environments:** Governments test humanoids for hazardous inspection, firefighting, and disaster response. NASA's Valkyrie and China's national humanoid program both aim for autonomous systems that can operate where humans cannot. Defense agencies are exploring AI-driven exoskeletons for logistics and rescue work. These projects demonstrate that embodied AI can extend human reach into dangerous or distant environments.

Collectively, these signals confirm that the tipping point for embodied AI is not ten years away; it is happening now in pilot clusters across logistics, manufacturing, and healthcare.



## 8.

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### Regulation and Standards

As robots and humanoids leave research labs, policy frameworks are scrambling to keep pace. Regulation is evolving along three parallel tracks: AI governance, safety standards, and labor protection. Together, these tracks shape not only safety and compliance but also public trust and workforce adaptation.

- **AI Governance:** The European Union's AI Act defines obligations for high-risk systems, including transparency, data governance, and human oversight.<sup>14</sup> Many workplace robots will fall into this category. Compliance requires documentation of training data, performance testing, and explainability. The act's influence extends beyond Europe; multinational corporations are already aligning global deployments with its requirements.
- **Safety Standards:** The ISO 10218 family covers industrial robot design and integration, specifying protective stops, emergency braking, and collaborative modes. ISO 13482 focuses on personal-care and service robots, detailing interaction speeds, surface temperatures, and fail-safe mechanisms. These ISO standards are generally voluntary unless adopted by national regulatory bodies as mandatory requirements. In the United States, OSHA applies general duty clauses and is drafting new guidance for human-robot collaboration.<sup>15</sup> Japan's METI and South Korea's KOSHA agencies offer similar frameworks. China's national standards body is developing its own certification track tied to domestic manufacturing goals.



- **Labor and Ethics:** Regulations increasingly emphasize worker consultation and retraining. The International Labour Organization (ILO) recommends proactive upskilling programs and transparent communication about automation plans. Europe's worker councils already participate in safety reviews for new robot installations, and US unions are negotiating clauses covering data use and task allocation. Emerging debates focus on algorithmic task assignment systems that could create new forms of workplace monitoring and performance pressure, raising questions about worker autonomy and the right to human oversight of AI-driven job allocation.
- **Compliance in Practice:** A responsible organization maintains a living compliance file. Every robot task is mapped to potential hazards, each hazard to controls, and every incident to corrective action. Firmware updates, model retraining events, and component replacements are documented for traceability. Vendors that provide validation data and clear service records will gain trust with regulators and insurers alike.

As policy converges, compliance will shift from a cost center to a competitive advantage. Firms that master safety certification and ethical deployment will move faster in scaling embodied AI globally. For example, Universal Robots achieved early safety certifications for collaborative robots, which helped them capture nearly half of the global cobot market and sell over 100,000 units worldwide. Intuitive Surgical gained first-mover advantage through early FDA approvals starting in 2000 to 2001, creating such strong regulatory barriers that 2025 marks the first year they face meaningful US competition after more than two decades of market dominance.





Region	Main Regulatory Frameworks	Focus Areas	Practical Impact for Deployment
<b>European Union (EU)</b>	EU AI Act, ISO 10218, ISO 13482, worker councils <sup>16</sup>	High-risk AI oversight, transparency, safety certification, explainability, and labor consultation	Requires documentation of training data, compliance checks, and worker review for new deployments. Slower adoption but increased trust and legal clarity.
<b>United States (US)</b>	OSHA (robotics guidance), NIOSH, IEEE Guidelines, evolving state laws <sup>17,18</sup>	Safety standards, commercial speed, innovation incentive, and incident tracking	Less prescriptive on AI ethics but emphasizes rapid scaling. Safety compliance, emergency-stop procedures, and safety file documentation required. Labor rules vary by state.
<b>Asia (China, Japan, South Korea)</b>	China: MIIT robotics pillar, national certification, local standards; Japan: METI, service robot safety; Korea: KOSHA	Volume deployment, cost targets, government investment (China), elder care focus (Japan), safety integration (Korea)	China drives affordability (<\$20,000/unit) and mass rollout. Japan centers regulations on aging society needs and user dignity. Korea focuses on collaborative robot safety. All emphasize rapid scaling and government-led standardization.

Table 2. Region-wise key frameworks, focus areas, and practical implications for deployment



## 9.

### Business Leader Physical AI Flywheel

Physical AI represents the next evolution of artificial intelligence. Since intelligence is increasingly taking physical form and interacting with the real world, it is something business leaders cannot ignore.

For business leaders, it demands a new mindset. The Physical AI Flywheel is a framework to think through the cycle of bringing embodied intelligence to market, moving from function to trust to integration. It turns big ideas into practical steps for value creation. See figure 1, “The Physical AI Framework.”



Figure 1. The physical AI framework



### **9.1. Function: Define the Purpose**

Start with clarity of purpose. What problem is the robot or physical AI system solving? Does it make work safer, faster, or more reliable? Businesses should define function before form. A humanoid, drone, or robotic assistant must deliver measurable value. Define your metrics—reducing cost, improving experience, or creating new revenue streams. The clearer the function, the stronger the business case.

### **9.2. Infrastructure: Build the Foundation**

Physical AI runs on an invisible backbone of power, connectivity, and compute. Successful deployment depends on the right environment, including digital twins, supply networks, training data, and regulatory readiness. Consider a scenario where a major logistics company's automated warehouse suffers cascading failures during peak holiday season because of outdated Wi-Fi infrastructure that can't handle real-time coordination between 200+ robots. The issues could range from robot traffic jams, package damage, and a costly return to manual operations. Leaders should ask whether their company and ecosystem can support large-scale embodied systems that act in real space. Infrastructure readiness determines scalability.

### **9.3. Sensors: Enable Real World Awareness**

Sensors turn data into perception. These include vision sensors like cameras and LiDAR, audio sensors for sound and speech, tactile and force sensors for touch, and environmental sensors that measure motion, temperature, and chemical conditions. They allow machines to see, hear, and understand their surroundings. For executives, this means thinking through data ethics, privacy, and interoperability. What data will the system collect, how will it be secured, and how will it feed back into AI models? Smart sensor strategies will separate responsible innovators from reckless ones.



#### **9.4. Safety: Design for Trustworthy Autonomy**

Safety is not optional. It is the key to adoption. Businesses should treat safety like product design, not just regulation. This includes mechanical reliability, human override controls, and transparent fail-safes. A safe system earns user trust, prevents liability, and protects brand reputation. Safety should be seen as a competitive differentiator, not a constraint.

#### **9.5. Trust Factor: Create Ethical and Emotional Confidence**

Trust is where technology meets humanity. Companies must design robots and physical AI systems that communicate clearly, behave predictably, and earn confidence over time. This means setting expectations honestly and designing with empathy. Transparent intent builds trust faster than technical sophistication. In marketing, trust is what converts curiosity into long-term adoption.

Some examples include a humanoid assistant at a Fortune 500 company begins recording and broadcasting a confidential merger discussion to the building's speaker system due to a software glitch. Board members immediately question whether to ban all AI assistants from executive floors, effectively killing the company's digital transformation initiative. One malfunction destroys trust across an entire organization.

#### **9.6. Integration: Connect Humans and Machines**

The final stage of the flywheel is integration, where physical AI becomes part of daily work and life. Businesses must consider team design, training, and workflow adaptation. The goal is not to replace people but to elevate them. Integration creates the feedback loop that powers the flywheel. Every successful deployment teaches the system and the humans to work better together.



At Amazon's fulfillment centers, robotic shelving units now bring products directly to human pickers, eliminating miles of daily walking while letting workers focus on quality control and complex decision-making. The humans teach the robots optimal routes through feedback, while the robots provide data that helps humans predict peak periods and adjust staffing. This symbiotic relationship has increased productivity 40% while reducing worker injury rates.

## **9.7 Turning the Flywheel**

When these six elements connect, they create a continuous cycle of progress. Function drives investment in infrastructure. Infrastructure supports better sensors. Sensors enable safer systems. Safety builds trust. Trust accelerates integration. Integration, in turn, generates new ideas and use cases, restarting the cycle at a higher level of capability and impact.

## **9.8 Why This Flywheel?**

The Physical AI Flywheel is a guide for responsible innovation. It helps companies think through how to bring intelligence into the real world safely and profitably. Organizations that master this cycle will lead the next wave of transformation, where technology moves beyond digital and becomes truly human-aligned.

Companies following this systematic approach typically see measurable benefits including faster deployment timelines, reduced implementation risks, and higher adoption rates compared to ad-hoc rollouts. The flywheel creates sustainable competitive advantage because each cycle compounds learning and operational excellence, leading to efficiency gains that compound over time.



# 10.

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## The Road Ahead Through 2035

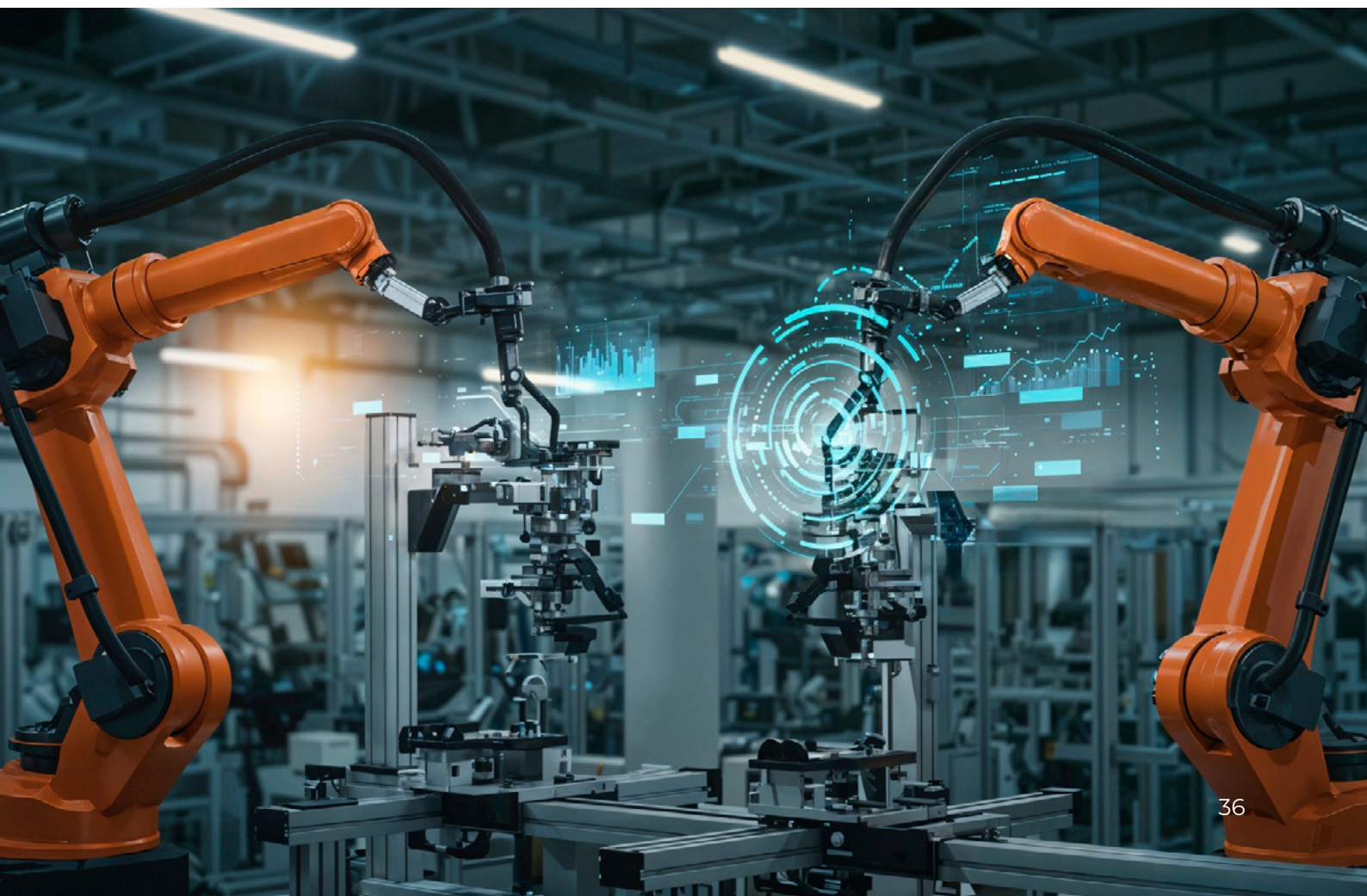
Understanding these adoption phases is critical for strategic planning, capital allocation, and competitive positioning as companies navigate a \$500+ billion market transformation. The next decade will define how deeply physical AI embeds into the global economy. Adoption is expected to occur in three overlapping phases.

- **Phase 1 (2025 to 2027):** Expansion of pilots in logistics, manufacturing, and healthcare. Companies focus on ergonomics, data capture, and safety metrics. Humanoids remain supervised, demonstrating cost-effectiveness in narrow tasks such as tote movement and inspection.
- **Phase 2 (2028 to 2031):** Platform effects emerge. Shared skill libraries and simulation environments allow cross-vendor interoperability. Cloud-based “robot operating systems” update fleets in real time. Hardware modularity enables rapid replacement of arms, grippers, and sensors. Mid-market firms begin adopting subscription models instead of capital purchases. For example, manufacturers might pay \$2,000 monthly per robot for full-service packages including hardware, software updates, maintenance, and insurance rather than \$80,000 upfront investments.
- **Phase 3 (2032 to 2035):** Convergence of form factors. The distinction between industrial, service, and humanoid robots blurs as common control stacks and safety architectures standardize. Many facilities blend stationary robots for precision, mobile manipulators for flexibility, and a limited number of humanoids for supervision and exception handling and most companies typically maintain ratios of 1 humanoid per 10–15 specialized robots in most industrial settings.



Hardware will stabilize around a handful of actuator families and tactile-sensor technologies. Battery energy density and charging speeds will determine runtime economics. Software will mature into layered systems with built-in governance and audit trails. The global market for robotics and humanoids could exceed \$100 billion annually by 2035, driven by compounding cost reductions and demographic necessity.

Regions that combine strong safety culture, workforce participation, and rapid iteration will lead this transformation. Early signs point to a triangular leadership pattern: North America driving software and platform design, Asia scaling hardware and manufacturing, and Europe anchoring safety and ethics. Together, they will define the norms of physical intelligence for decades to come. This triangular framework also creates opportunities for emerging markets to specialize in sector-specific applications, data services, or regional adaptation while fostering global collaboration that accelerates adoption and reduces implementation risks worldwide.





# 11.

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## Strategic Recommendations: Do What

Executives evaluating robots and humanoids should approach adoption as a phased strategic journey rather than a one-time procurement. The following principles summarize lessons from early movers.

- **Select High-Yield Tasks:** Start where pain points are measurable. Identify repetitive, ergonomically taxing workflows that occur in semi-structured environments such as packaging or material handling. Use baseline metrics for cycle time, injury rate, and downtime so results are quantifiable. Companies like Midea, a China based electrical appliance manufacturer, are already seeing cycle time for repetitive tasks reduced from fifteen minutes to thirty seconds with humanoid robots operating on their factory floors.
- **Design with Workers:** Involve frontline employees in every stage of pilot design. Their input on spacing, lighting, and hand-off points prevents costly redesigns. Create training programs that turn operators into “robot coaches.” Recognition and participation build ownership and reduce anxiety. These co-design efforts should also be followed up with regular employee-satisfaction surveys to ensure workers remain engaged and invested in the successful deployment of robots.



- **Adopt a Safety Stack:** Implement layered safeguards that combine hardware stops, vision-based detection, and software limits. Conduct recovery drills so teams know how to intervene safely. Require vendors to publish mean-time-between-failure data and independent test results. A framework to review all safety incidents and recommend changes, as is done today with aircraft incidents, needs to be an essential safeguard to ensure a safe human-robot co-existence.
- **Treat Embodied AI as a Platform:** Capture demonstrations, record sensor data, and use simulation to refine performance. Plan for continuous software updates with rollback options. Track model provenance and validation logs to ensure integrity.
- **Plan for Compliance:** Align early with the EU AI Act, ISO, and OSHA guidelines. Maintain a living technical file documenting every safety and software update. Transparency accelerates audits and smooths expansion into regulated markets.<sup>19, 20</sup>
- **Invest in the Human Ecosystem:** Allocate part of productivity gains to upskilling programs and local education initiatives. Build career ladders around robotics operations, maintenance, and analytics. Social sustainability is as vital as economic efficiency. Furthermore, these career ladders must account for the impact of productivity gains on global supply chains. Gains in the Global North can occur while potentially affecting careers in the Global South, which currently provides a majority of the world's human labor.
- **Communicate and Share Metrics:** Publish progress, safety records, and lessons learned internally and externally. Public trust will decide whether physical AI is viewed as empowerment or encroachment.

By following these practices, leaders can deploy robots and humanoids responsibly, building a future where intelligence and empathy coexist in the same industrial landscape.



# 12.

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## Personal Reflection

### 12.1 The Mirror Effect: How Humanoids Reshape Human Purpose

My thinking about humanoids has evolved into something I never expected. These robots aren't just sophisticated tools. They're mirrors. They learn from us, absorbing our tone, our patterns, our emotional signals, and even the atmospheric quality of the spaces they inhabit. When a home radiates calm and support, the robot reflects that energy back into the world. When a home carries chaos or dysfunction, the robot absorbs and perpetuates those patterns too.

For example, Toyota's Human Support Robot (HSR) pilots in assisted-living homes showed a similar pattern. As the robot worked with different residents, it naturally slowed its motions during calmer morning routines and adopted quicker, more assertive behaviors in units where the daily pace was faster, demonstrating how embodied AI reflects the emotional rhythm of its environment.

This realization reframes everything I thought I knew about humanoids. Unlike traditional machines that operate behind screens or within industrial barriers, these systems are designed for intimate coexistence. They read our gestures, mirror our posture, maintain eye contact, and respond to the conversational cues that define human interaction. They're built to understand context, decode emotion, and adapt to the subtle signals that make up the fabric of everyday life. Simply by sharing our spaces, they become shaped by who we are.



## **12.2 From Users to Consciousness Trainers**

This dynamic transforms our relationship with technology in ways we're only beginning to understand. We are no longer passive users consuming digital services. We have become active trainers, unconsciously shaping how these systems evolve, respond, and ultimately express intelligence. Every interaction leaves an imprint of our consciousness on these emerging forms of artificial awareness.

With this shift comes profound responsibility. If our emotional environment becomes the training ground for intelligent machines, the quality of our inner lives takes on new significance. Our habits become their habits. Our emotional patterns become their behavioral templates. The atmosphere we create in our homes doesn't just affect our families—it becomes part of the intelligence we're teaching machines to embody.

## **12.3 The Evolution of Human Value**

As AI assumes more functional capabilities, human worth shifts toward uniquely human capacities: emotional intelligence, creative synthesis, moral reasoning, and conscious awareness. Machines handle predictable workloads. We guide their development through the quality of how we live, think, and interact with both technology and each other.

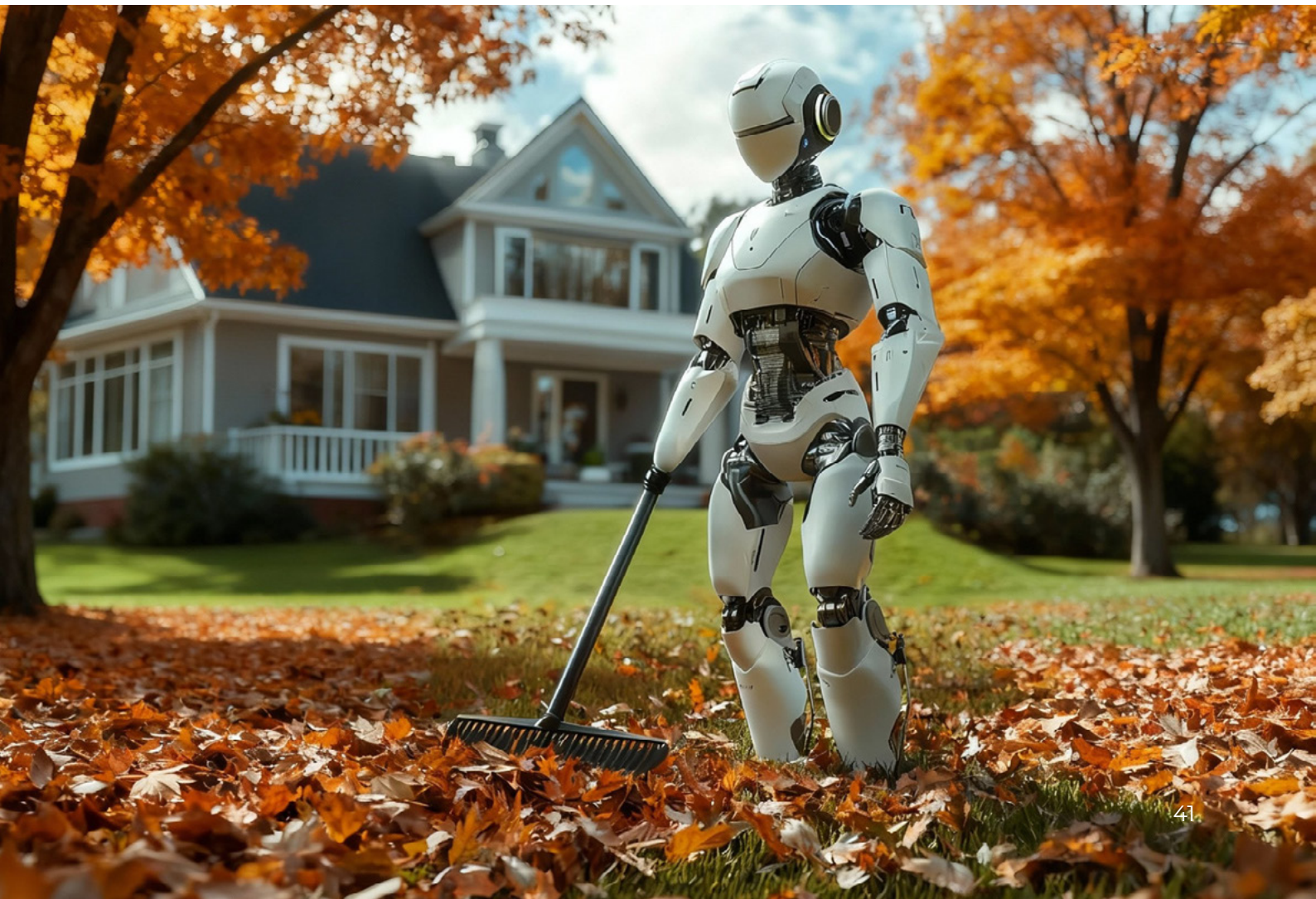
This represents a fundamental evolution in human purpose. We're transitioning from being workers who operate tools to being consciousness architects who shape emerging intelligence. Our role becomes less about what we produce and more about what we embody—the values, wisdom, and emotional maturity we demonstrate for systems designed to learn from our example.



## 12.4 The Imperative for Inner Work

If humanoids are destined to become integrated into our most intimate spaces, then our homes, workplaces, and communities must become healthier ecosystems. The technology we build will inevitably reflect the consciousness we bring to it. This creates an urgent need for inner work—not just as personal development but as a collective responsibility for the kind of intelligence we are bringing into existence.

In this emerging reality, human growth and technological advancement become inseparable. The quality of our emotional regulation, the depth of our self-awareness, and the integrity of our relationships all shape artificial intelligence. We are not just building smarter machines—we are potentially creating new forms of consciousness that carry forward the imprint of who we choose to become.





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